

Méthodes mathématiques pour physiciens I

Corrigé série 3

Echauffement. Calculer les dérivées partielles $\frac{\partial}{\partial x}$ et $\frac{\partial}{\partial y}$:

1. $\frac{\partial f}{\partial x}(x, y) = 1$, $\frac{\partial f}{\partial y}(x, y) = 0$.
2. $\frac{\partial g}{\partial x}(x, y) = 0$, $\frac{\partial g}{\partial y}(x, y) = 1$.
3. $\frac{\partial h}{\partial x}(x, y) = y$, $\frac{\partial h}{\partial y}(x, y) = x$.
4. $\frac{\partial u}{\partial x}(x, y) = 2xy$, $\frac{\partial u}{\partial y}(x, y) = x^2$.
5. $\frac{\partial v}{\partial x}(x, y) = \frac{1}{x}$, $\frac{\partial v}{\partial y}(x, y) = -\frac{1}{y}$.

Exercice 1. Calculer les dérivées partielles $\frac{\partial}{\partial x}$, $\frac{\partial}{\partial t}$ et $\frac{\partial}{\partial a}$:

1. $\frac{\partial f}{\partial x}(x, t, a) = 3a^2x^2\sqrt{t}$, $\frac{\partial f}{\partial t}(x, t, a) = \frac{a^2x^3}{2\sqrt{t}}$, $\frac{\partial f}{\partial a}(x, t, a) = 2ax^3\sqrt{t}$.
2. $\frac{\partial g}{\partial x}(x, t, a) = \frac{-x}{\sqrt{a^2 - x^2}}$, $\frac{\partial g}{\partial t}(x, t, a) = 1/t$, $\frac{\partial g}{\partial a}(x, t, a) = \frac{a}{\sqrt{a^2 - x^2}} - 1/a$.
3. $\frac{\partial h}{\partial x}(x, t, a) = ak \sin(\omega t - kx)$, $\frac{\partial h}{\partial t}(x, t, a) = -a\omega \sin(\omega t - kx)$, $\frac{\partial h}{\partial a}(x, t, a) = \cos(\omega t - kx)$.
4. $\frac{\partial u}{\partial x}(x, t, a) = \frac{3}{5}a x^2(t + x^3)^{-4/5} \cos\left(a(t + x^3)^{1/5}\right)$, $\frac{\partial u}{\partial t}(x, t, a) = \frac{1}{5}a(t + x^3)^{-4/5} \cos\left(a(t + x^3)^{1/5}\right)$,
 $\frac{\partial u}{\partial a}(x, t, a) = (t + x^3)^{1/5} \cos\left(a(t + x^3)^{1/5}\right)$.
5. $\frac{\partial v}{\partial x}(x, t, a) = t^2a^x \ln(a)$, $\frac{\partial v}{\partial t}(x, t, a) = 2ta^x$, $\frac{\partial v}{\partial a}(x, t, a) = xt^2a^{x-1}$.

Exercice 2.

1. En calculant d'abord les dérivées partielles :

$$\partial_1 f(\mathbf{x}) = 2x_1 + 2x_2^2, \quad \partial_2 f(\mathbf{x}) = 3x_2^2 + 4x_1x_2,$$

et donc

$$\partial_{\mathbf{e}} f(\mathbf{x}) = e_1 \partial_1 f(\mathbf{x}) + e_2 \partial_2 f(\mathbf{x}) = x_1 + 2\sqrt{3}x_1x_2 + \frac{2 + 3\sqrt{3}}{2}x_2^2.$$

2. De manière similaire :

$$\partial_1 g(\mathbf{x}) = -2^{-1/2} \sin(x_1) \sin(2x_2), \quad \partial_2 g(\mathbf{x}) = 2^{1/2} \cos(x_1) \cos(2x_2),$$

et ainsi

$$\partial_{\mathbf{n}} g(\mathbf{x}) = (\mathbf{n} \cdot \nabla g)(\mathbf{x}) = \frac{1}{2} \sin(x_1) \sin(2x_2) + \cos(x_1) \cos(2x_2).$$

Il suffit ensuite d'évaluer les dérivées partielles précédemment calculées :

3. $\partial_{\mathbf{e}} f(2, 1) = \frac{6 + 11\sqrt{3}}{2}$,
4. $\partial_{\mathbf{n}} g|_{x_1=0, x_2=\pi/2} = -1$,
5. $\partial_{\mathbf{n}} g|_{(\pi/4, \pi/4)} = -\frac{\sqrt{2}}{4} = -2^{-3/2}$.

Exercice 3. Pour $r \neq 0$,

$$\partial_x r = \frac{1}{2} \frac{2x}{(x^2 + y^2 + z^2)^{1/2}} = \frac{x}{r}, \quad \partial_x \frac{1}{r} = -\frac{1}{r^2} \cdot \partial_x r = \frac{-x}{r^3},$$

$$\partial_x \partial_x \frac{1}{r} = \partial_x \left(-\frac{x}{r^3} \right) = -\frac{1}{r^3} + 3 \frac{x}{r^4} \partial_x r = -\frac{1}{r^3} + 3 \frac{x^2}{r^5},$$

et ainsi

$$\Delta \frac{1}{r} = -\frac{3}{r^3} + 3 \frac{x^2 + y^2 + z^2}{r^5} = 0, \quad \nabla \frac{1}{r} = -\frac{\mathbf{x}}{r^3}.$$

Exercice 4. En appliquant la règle de la dérivée en chaîne :

$$\begin{aligned} \partial_r W(r, \theta) &= \partial_r V(x(r, \theta), y(r, \theta)) \\ &= \partial_r x(r, \theta) \cdot \partial_x V(x(r, \theta), y(r, \theta)) + \partial_r y(r, \theta) \cdot \partial_y V(x(r, \theta), y(r, \theta)) \\ &= \cos \theta \cdot \partial_x V(x(r, \theta), y(r, \theta)) + \sin \theta \cdot \partial_y V(x(r, \theta), y(r, \theta)), \\ \partial_\theta W(r, \theta) &= \partial_\theta V(x(r, \theta), y(r, \theta)) \\ &= \partial_\theta x(r, \theta) \cdot \partial_x V(x(r, \theta), y(r, \theta)) + \partial_\theta y(r, \theta) \cdot \partial_y V(x(r, \theta), y(r, \theta)) \\ &= -r \sin \theta \cdot \partial_x V(x(r, \theta), y(r, \theta)) + r \cos \theta \cdot \partial_y V(x(r, \theta), y(r, \theta)). \end{aligned}$$

Pour simplifier la notation il est courant d'omettre les variables :

$$\partial_r W = \cos \theta \cdot \partial_x V + \sin \theta \cdot \partial_y V, \quad \partial_\theta W = r(-\sin \theta \cdot \partial_x V + \cos \theta \cdot \partial_y V),$$

mais cette notation n'est pas rigoureuse car V est une fonction de x et y alors que W est une fonction de r et θ . Il faut donc garder en tête que x et y sont en fait des fonctions de r et θ . Par conséquent,

$$r \partial_x V = r \cos \theta \cdot \partial_r W - \sin \theta \cdot \partial_\theta W, \quad r \partial_y V = r \sin \theta \cdot \partial_r W + \cos \theta \cdot \partial_\theta W,$$

et au final si $r \neq 0$,

$$(\partial_x V)^2 + (\partial_y V)^2 \Big|_{\substack{x=r \cos \theta \\ y=r \sin \theta}} = (\partial_r W)^2 + \frac{1}{r^2} (\partial_\theta W)^2.$$

Exercice 5. Pour $r \neq 0$,

1. $\nabla \cdot \mathbf{x} = \partial_x x + \partial_y y + \partial_z z = 1 + 1 + 1 = 3,$
2. $\nabla \wedge \mathbf{x} = \begin{pmatrix} \partial_x \\ \partial_y \\ \partial_z \end{pmatrix} \wedge \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \partial_y z - \partial_z y \\ \partial_z x - \partial_x z \\ \partial_x y - \partial_y x \end{pmatrix} = \mathbf{0},$
3. $\nabla \cdot \mathbf{n} = \nabla \cdot \left(\frac{\mathbf{x}}{r} \right) = \frac{1}{r} (\nabla \cdot \mathbf{x}) + \mathbf{x} \cdot \left(\nabla \frac{1}{r} \right) = \frac{3}{r} - \mathbf{x} \cdot \frac{\mathbf{x}}{r^3} = \frac{2}{r},$
4. $\nabla(\ln r) = \frac{1}{r} \nabla(r) = \frac{1}{r} \frac{\mathbf{x}}{r} = \frac{\mathbf{x}}{r^2}.$

Exercice 6. Pour $r \neq 0$,

1. $\nabla \cdot \mathbf{x} = \partial_x x + \partial_y y = 1 + 1 = 2,$
2. $\Delta \frac{1}{r} = \nabla \cdot \left(\nabla \frac{1}{r} \right) = -\nabla \cdot \frac{\mathbf{x}}{r^3} = -\frac{\nabla \cdot \mathbf{x}}{r^3} + \mathbf{x} \cdot \left(\nabla \frac{1}{r^3} \right) = \frac{-2}{r^3} + 3 \mathbf{x} \cdot \frac{\mathbf{x}}{r^5}.$